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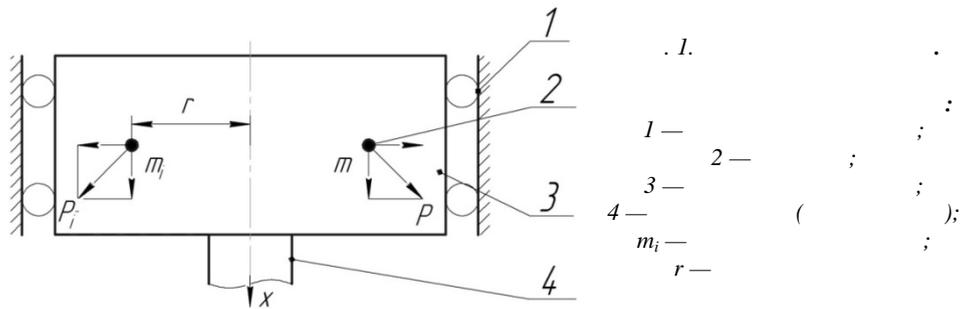
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PIPE STRING VIBRATIONS CAUSED BY TOP DRIVE RIG MASS IMBALANCE

E. A. Petrovsky, K. A. Bashmur

Key words: top drive system (TDS), drilling rig, drilling string, vibrations, drill tower

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$$(P \cdot \sin \omega t)$$

ω

[1].

$$P(t) = P_{\max} \sin(\omega t + \phi) = \sum_{i=1}^N P_i \sin(\omega t + \phi) = \sum_{i=1}^N m_i r \omega^2 \sin(\omega t + \phi). \quad (1)$$

$$\begin{cases} Ma_z = P_z - P_{z_c} - P_z \\ Ma_y = P_y - P_{y_c} - P_y \end{cases}, \quad (2)$$

M — ; z, y — x ;
 P_c — ; P —

$$\begin{cases} Mz'' = P_{\max} \cos(\omega t + \phi) - \beta z' - kz, \\ My'' = P_{\max} \sin(\omega t + \phi) - \beta y' - ky, \end{cases} \quad (3)$$

(); k —
 M (2),

$$\begin{cases} \frac{d^2 z}{dt^2} + 2n \frac{dz}{dt} + k_d^2 z = p_{\max} \cos(\omega t + \phi), \\ \frac{d^2 y}{dt^2} + 2n \frac{dy}{dt} + k_d^2 y = p_{\max} \sin(\omega t + \phi), \end{cases} \quad (4)$$

$$k_d^2 = \frac{k}{M} \quad ; \quad n = \frac{\beta}{2M}$$

$$; \quad p_{\max} = \frac{P_{\max}}{M}$$

$$(4) \quad \dots \quad n \quad \dots \quad n$$

$$u(t) = \hat{u}_0 e^{i\nu t}, \quad (5)$$

$$u = z + iy; \hat{u}_0 = u_0 e^{i\varphi} \quad ; u_0 \text{ —}$$

$$\hat{P}(t) = \hat{p}_{max} e^{i\nu t}. \quad (6)$$

(4)

$$u'' + 2nu' + k_d^2 u = \hat{p}_{max} e^{i\nu t}. \quad (7)$$

(6)

$$\hat{u}_0 \quad , \quad w. \quad (5) \quad (7)$$

$$(-w^2 + 2in\nu + k_d^2) \hat{u}_0 e^{i\nu t} = \hat{p}_{max} e^{i\nu t}. \quad (8)$$

$$\hat{u}_0 = \frac{\hat{p}_{max}}{k_d^2 - w^2 + 2in\nu}. \quad (9)$$

$$u_0 = \frac{P_{max}}{M \sqrt{(k_d^2 - w^2)^2 + (2nw)^2}} = \frac{rw^2 \sum_{i=1}^N m_i}{M \sqrt{(k_d^2 - w^2)^2 + (2nw)^2}}, \quad (10)$$

[2]

$$tg\varphi = \frac{Im\hat{u}_0}{Re\hat{u}_0} = \frac{2nw}{w^2 - k_d^2}. \quad (11)$$

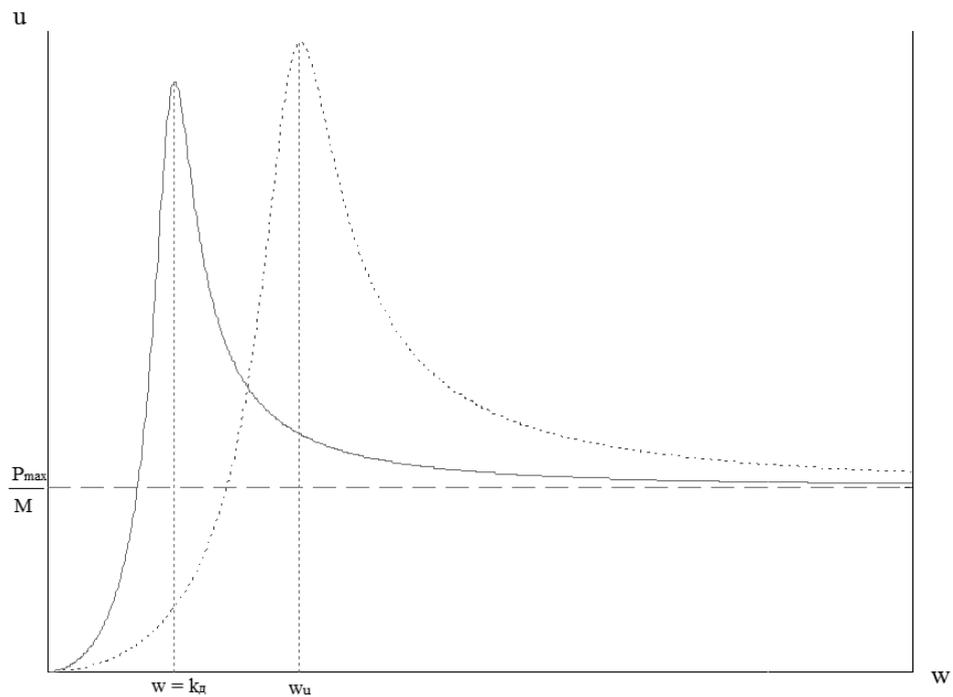
(10)

$$w_u = \frac{k^2}{\sqrt{k^2 - 2n}},$$

$$w = k \quad (\quad . 2).$$

$$\frac{P_{max}}{M} ($$

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MATHEMATICAL MODELLING OF GROUND-SURFACE PIPELINES
 INTERACTING WITH ENVIRONMENT

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Key words: heat pipeline, heat insulation

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